

Defense Science and Technology Seminar On Emerging Technologies



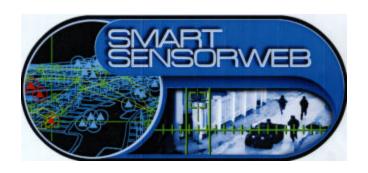


Image and Simulation Webs 13 November 2000

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Smart Sensor Web Objectives



SSW Vision: An intelligent, web-centric distribution and fusion of sensor information . . . that provides greatly enhanced situational awareness, on demand, to Warfighters at lower echelons.

"... emphasizes large arrays of local sensors joined with other assets: imagery, weather, weapons, simulations, etc. . . ."

Jump-start the acquisition process for SSW by leveraging Service & DARPA efforts

Develop, through experimentation, a conceptual system design for SSW

- Enhanced situational awareness
- On-demand intelligent information
 Images, weather, weapons, etc.
- Available to lower echelons
- Rapid weapon response

"Tactical and engagement level <u>situation awareness</u>, and <u>extended range tactical engagement</u> (including beyond line-of-sight), have the <u>highest payoff</u> of any protection option."

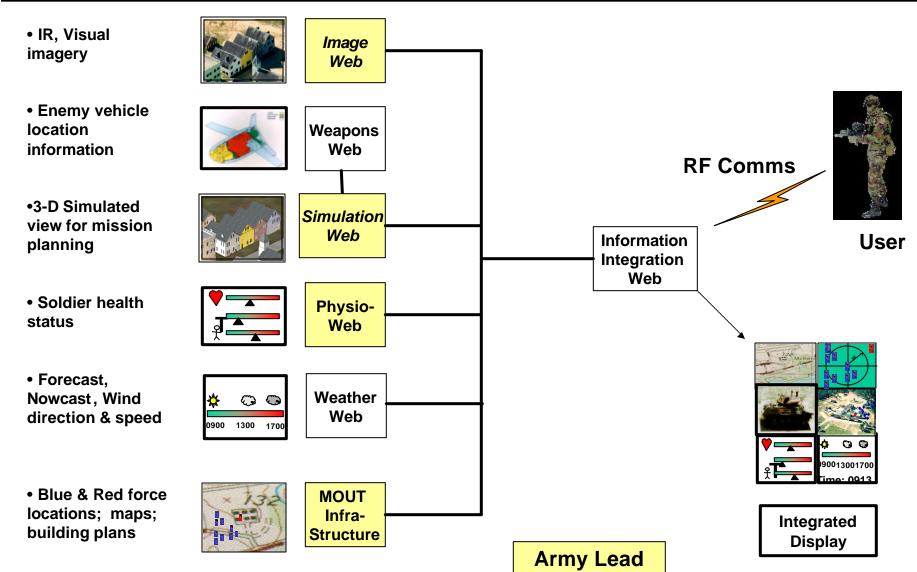
(FY99 - Army Science Board)

SSW Complements and Assists Army SA Programs



Smart Sensor Web *Integrated Products*





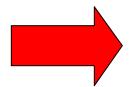


Smart Sensor Web Image Web





Demonstrate efficient methods to put "eyes on target"



<u>Testbed Approach</u>: Utilize low-power, non-imaging sensors to detect activity and trigger imagers.

Saves POWER and BANDWIDTH

FY00 Highlights:

- Established flexible testbed to assess utility of distributed sensors
- Obtained valuable feedback from soldiers
- IW Web Page (http://206.246.112.22)

Path Forward:

- Wireless, infrared fire-team imager
- Additional phenomenologies (radar, chem-bio)
- Data compression techniques
- UAV

Testbed Hardware (August 2000)





Uncooled, micro-bolometer, infrared imager [NVESD]



UGV with acoustic array, cued vis/IR imager [ARL]

Omni-directional imaging and tracking [DARPA]



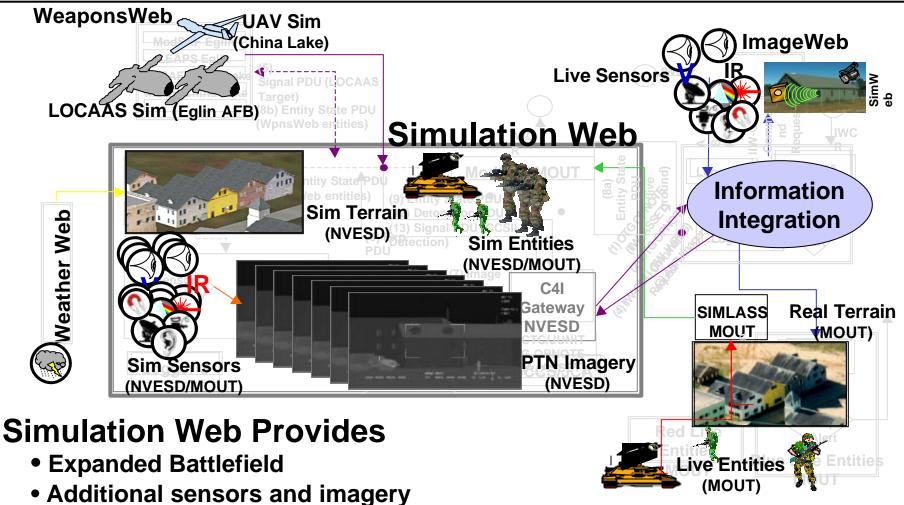
Non-imaging trigger sensors (mag, acoustic, seismic, PIR)





Simulation Web Distributed Live/Virtual Testbed





• Interface between Weapons and Live Entities to Information Integration

Simulation Experiments to supplement live experiments
Common terrain for all simulators



Smart Sensor Web Benefits to the Army's Vision



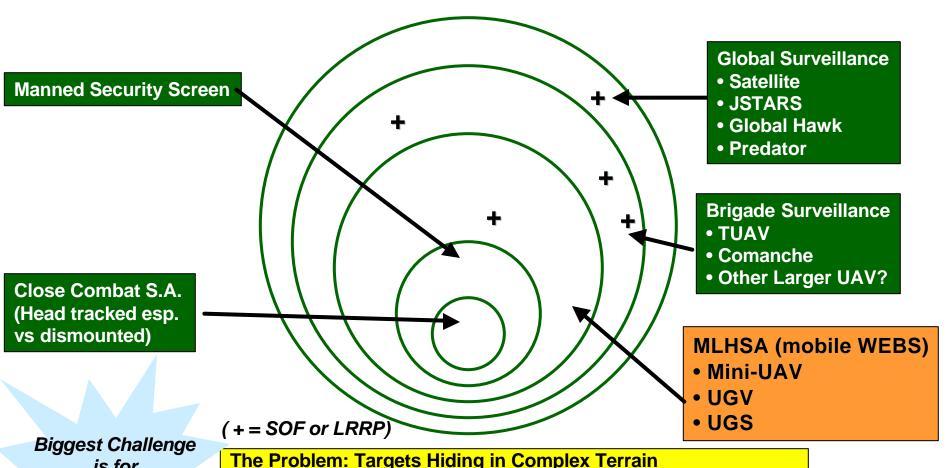
- Established the infrastructure for the conduct of user evaluations (McKenna MOUT site)
 - Conducted APLA Experiments using SSW Data collection and Uncooled IR (30 Oct –3 Nov)
- <u>Acquired the 1st generation Low Cost Uncooled IR Cameras</u> and allowed initial field evaluation
- SSW allow <u>validated of the overarching sensor architecture</u> for the Army's SA and APLA requirements – "early warning followed by confirming imagery"
- <u>Development of sensor simulation and communication effects</u> for Robust man in the loop simulation
- <u>Establishment of high fidelity MOUT Terrain data base</u> to conduct Man in the Loop simulation runs
- Obtained initial user feedback on the utility of distributed sensors for beyond line of sight (BLOS) Situational Awareness



Layered Surveillance for the Objective Force/FCS



Goal: Complete Situation Awareness and Timely BLOS Targeting (Avoid Unintentional Close Combat)



is for offensive operations

The Solution: Networked Unmanned Sensors

Multiple Look Angles (High and Low)

Continuous Tracking with Cross Cueing

Last Resort: Manned Security Screen

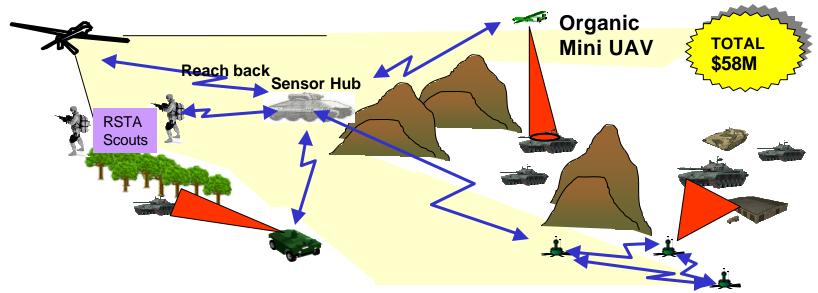


Sensors for the Objective Force (SfOF)

STO III.IS.2001.02 (FY02-05)



Objective: Develop a new generation of low cost sensor systems for manned and unmanned scouts, robotic vehicles and UAVs that move with the force



Enabling Technologies:

- Low cost unattended sensor payloads for mini-UAVs, UGVs and UGS
 - uncooled IR
 - Eyesafe laser gated SWIR imaging
- Use "reach back" links, and develop data fusion & smart sensor management tools to optimize the deployment of mobile sensors

Warfighter Payoffs:

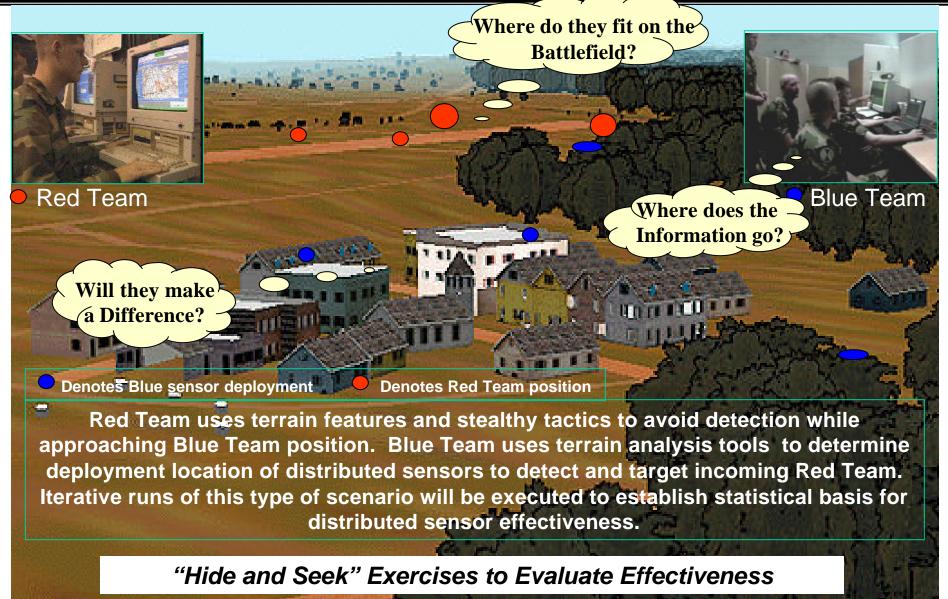
- Demonstrate mobile sensors systems for BLOS SA for enhancing survivability and lethality
- More organic coverage area per scout
- Supports Objective Force concept development

Distributed Sensors Fill the SA Gaps – Complements Global Surveillance



Sensors for the Objective Force Virtual Simulation Strategy







Smart Sensor Web Conclusions and Recommendations



CONCLUSIONS:

- An Organic Distributed Sensor Network offers the means for the Army's Objective Force and Marine Expeditionary Commanders to argument their Situational Understanding (SU) by filling the gaps in the higher echelon surveillance
- OSD SSW products and lessons learn feed directly into the Army ATD proposal for "Sensors for the Objective Force" and will reduce transition risk for the ATD.

RECOMMENDATIONS:

- OSD SSW and Army Sensors for the Objective Force efforts coordinate to maximize SSW resources and transition opportunities
- Use OSD SSW to develop the integration of distributed sensor data into the Common Operational Picture (COP) in a joint Army/USMC environment.
- Reinstate scalability and mobility experiments